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ON GRAPHS WITH AN EIGENVALUE OF MAXIMAL MULTIPLICITY

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Abstract

Let G be a graph of order n with an eigenvalue $\mu \neq -1, 0$ of multiplicity $k < n - 2$. It is known that $k \leq n + \frac{1}{2} - \sqrt{2n + \frac{1}{4}}$, equivalently $k \leq \frac{1}{2}t(t-1)$, where $t = n - k > 2$. The only known examples with $k = \frac{1}{2}t(t-1)$ are $3K_2$ (with $n = 6$, $\mu = 1$, $k = 3$) and the maximal exceptional graph G_{36} (with $n = 36$, $\mu = -2$, $k = 28$). We show that no other example can be constructed from a strongly regular graph in the same way as G_{36} is constructed from the line graph $L(K_9)$.

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1 Introduction

Let G be a graph of order n with an eigenvalue $\mu \neq -1, 0$ of multiplicity $k < n - 2$. It was shown in [1] that $k \leq n + \frac{1}{2} - \sqrt{2n + \frac{1}{4}}$, equivalently $k \leq \frac{1}{2}t(t - 1)$, where $t = n - k > 2$. The only known examples with $k = \frac{1}{2}t(t - 1) > 1$ are $3K_2$, with spectrum $-1^{(3)}, 1^{(3)}$, and the unique maximal exceptional graph of order 36, with spectrum $21, 5^{(7)}, -2^{(28)}$. The latter graph is described in [3, Chapter 6] and [4, Example 5.2.6(a)]; it is denoted here by G_{36} . After a decade, it remains a problem to determine all the graphs with $k = \frac{1}{2}t(t - 1)$. The restricted question, of similar standing, is whether further examples can be constructed from a strongly regular graph in the same way that G_{36} is constructed from the line graph $L(K_9)$. Here we answer this question in the negative.

To describe the construction we recall some notation and terminology from [4]. For a subset X of the vertex set $V(G)$, we write \bar{X} for $V(G) \setminus X$, $G - X$ for the subgraph of G induced by \bar{X} , and G_X for the graph obtained from G by switching with respect to X . We say that X is a *star set* for μ if $|X| = k$ and μ is not an eigenvalue of $G - X$. Our main result is the following.

Theorem 1.1. *Let G be a graph of order $\frac{1}{2}t(t+1)$ ($t > 2$) with an eigenvalue $\mu \notin \{-1, 0\}$ of multiplicity $\frac{1}{2}t(t - 1)$. Suppose that G has a star set X for μ such that (i) $X \dot{\cup} \bar{X}$ is an equitable partition of G , (ii) G_X is a strongly regular graph. Then $t = 8$, $\mu = -2$ and $G = G_{36}$.*

Note that, in the situation of Theorem 1.1, $X \dot{\cup} \bar{X}$ is also an equitable partition of G_X . To construct G_{36} , we take $G_X = L(K_9)$ and choose X so that X induces $L(K_8)$ and \bar{X} induces K_8 .

2 Prerequisites

If X is a star set for μ in G , then $G - X$ is said to be a *star complement* for μ in G . Star sets and star complements exist for any eigenvalue of any graph, and their basic properties are described in [4, Chapter 5]. In particular, we shall require the following result.

Theorem 1.1 [4, Theorem 5.1.7] *Let X be a set of k vertices in the graph G and suppose that G has adjacency matrix $A = \begin{pmatrix} A_X & B^T \\ B & C \end{pmatrix}$, where A_X is the adjacency matrix of the subgraph induced by X . Then X is a star set for μ in G if and only if μ is not an eigenvalue of C and*

$$\mu I - A_X = B^T(\mu I - C)^{-1}B. \quad (1)$$

Suppose that X is a star set, and let $H = G - X$. In Theorem 1.1, k is the multiplicity of μ , and C is the adjacency matrix of H . Also, the columns of B are the characteristic vectors of the H -neighbourhoods

$$\Delta_H(u) = \{v \in V(H) : u \sim v\} \quad (u \in X),$$

where we write ' $u \sim v$ ' to mean that vertices u, v are adjacent in G . Equation (1) shows that any graph is determined by an eigenvalue μ , a star complement $H = G - X$ and the H -neighbourhoods of vertices in X . When $G - X$ is complete, we obtain the following by equating diagonal entries in Equation (1).

Lemma 2.2. *Suppose that X is a star set for μ in the graph G . Let $H = G - X$, $u \in X$. If $H = K_t$ ($t > 2$) and $|\Delta_H(u)| = a$ then*

$$a^2 - (t - \mu - 1)a + \mu(\mu + 1)(t - \mu - 1) = 0.$$

In the general case, we let $|V(H)| = t > 2$ and define a bilinear form on \mathbb{R}^t by

$$\langle\langle \mathbf{x}, \mathbf{y} \rangle\rangle = \mathbf{x}^\top (\mu I - C)^{-1} \mathbf{y} \quad (\mathbf{x}, \mathbf{y} \in \mathbb{R}^t).$$

We let $V(G) = \{1, 2, \dots, n\}$ and write $S = (B|C - \mu I)$, with columns \mathbf{s}_u ($u = 1, \dots, n$). Let \mathcal{Q}_t denote the space of homogeneous quadratic functions on \mathbb{R}^t . We define $F_1, \dots, F_n \in \mathcal{Q}_t$ by

$$F_u(\mathbf{x}) = \langle\langle \mathbf{s}_u, \mathbf{x} \rangle\rangle^2 \quad (\mathbf{x} \in \mathbb{R}^t).$$

Lemma 2.3. [1, Lemma 2.2] *If $t > 2$ and $\mu \neq -1$ or 0 , the functions F_1, \dots, F_n are linearly independent.*

Since $\dim \mathcal{Q}_t = \binom{t}{2} + t$, we deduce that $n \leq \binom{t}{2} + t$, equivalently $k \leq \binom{t}{2}$. The following result enables us to dispose of the regular graphs for which this bound is attained.

Theorem 2.4. [1, Theorem 3.1] *Let G be an r -regular graph G of order n with μ as an eigenvalue of multiplicity k . If $\mu \notin \{-1, 0, r\}$ and $t = n - k > 2$ then $k \leq \binom{t}{2} - 1$.*

Corollary 2.5. *If G is a regular graph of order $\frac{1}{2}t(t+1)$ ($t > 2$) with an eigenvalue $\mu \notin \{-1, 0\}$ of multiplicity $\frac{1}{2}t(t-1)$ then $t = 3$, $\mu = 1$ and $G = 3K_2$.*

Proof. If G is r -regular then $\mu = r$ by Theorem 2.4, and so G has $\frac{1}{2}t(t-1)$ components, each with μ as a simple eigenvalue (cf. [4, Corollary 1.3.8]). It follows that $t \geq \frac{1}{2}t(t-1)$, and hence that $t = 3$, $G = 3K_2$, $\mu = 1$. \square

Next, using Equation (1), we see that

$$\mu I - A = S^\top (\mu I - C)^{-1} S,$$

and so, for all vertices u, v of G ,

$$\langle\langle \mathbf{s}_u, \mathbf{s}_v \rangle\rangle = \begin{cases} \mu & \text{if } u = v \\ -1 & \text{if } u \sim v \\ 0 & \text{otherwise} \end{cases}. \quad (2)$$

It follows that if $\mu \notin \{-1, 0\}$ then the H -neighbourhoods $\Delta_H(u)$ ($u \in X$) are distinct and non-empty. When $k = \binom{t}{2}$, our objective will be to show that, under suitable conditions, the H -neighbourhoods form a tight 4-design, that is, a design which satisfies the following conditions with $s = 2$.

Theorem 2.6. [2, Theorem 1.52] *Let \mathcal{B} be a collection of a -subsets of the t -set V , where $2s \leq a \leq t - s$. Then any two of the following conditions imply the third.*

- (a) (V, \mathcal{B}) is a $2s$ -design;
- (b) there are precisely s values for the numbers $|B \cap B'|$, where B, B' are distinct sets in \mathcal{B} ;
- (c) $|\mathcal{B}| = \binom{t}{s}$.

Finally we can exploit the fact that tight 4-designs are extremely rare:

Theorem 2.7. [2, Theorem 1.54] *Let \mathcal{D} be a tight 4- (t, a, l) design with $4 \leq a < t - 2$. Then either \mathcal{D} or its complement $\overline{\mathcal{D}}$ is the unique 4- $(23, 7, 1)$ design.*

3 Proof of the main result

We retain the notation of the previous sections. Additionally we suppose that $k = \frac{1}{2}t(t-1)$ ($t > 2$), and that the star set X for $\mu \neq -1, 0$ is such that (i) $X \dot{\cup} \overline{X}$ is an equitable partition of G , (ii) G_X is strongly regular with parameters (n, r, e, f) ($0 < r < n - 1$). We show first that $t \neq 3$ by inspecting the strongly regular graphs of order 6. If $G_X = 2K_3$ or $\overline{2K_3}$ then there is no suitable bipartition $X \dot{\cup} \overline{X}$. If $G_X = 3K_2$ then $G - X = 3K_1$ and $G = C_6$, while if $G = \overline{3K_2}$ then $G - X = K_3$ and $G = \overline{C_6}$. In both cases G has no eigenvalue of multiplicity 3. Hence $t > 3$ and $k > \frac{1}{2}n$. It follows that μ is an integer, for otherwise μ has an algebraic conjugate which is a second eigenvalue of multiplicity k .

The partition $X \dot{\cup} \overline{X}$ determines divisors of G and G_X , and we denote the corresponding divisor matrices by

$$D = \begin{pmatrix} p & a \\ b & q \end{pmatrix}, \quad D^* = \begin{pmatrix} p & t - a \\ k - b & q \end{pmatrix},$$

respectively. Note that $|\Delta_H(u)| = a$ for all $u \in X$, and that $1 < a < t - 1$. In what follows, we write \mathbf{j} for an all-1 vector (with length determined by context), and A^* for the adjacency matrix of G_X . Additionally, \mathcal{E} denotes an eigenspace of G and \mathcal{E}^* denotes an eigenspace of G_X .

Lemma 3.1. *There exist integers λ, ρ such that G_X has spectrum $r, \lambda^{(t)}, \mu^{(k-1)}$ and G has spectrum $\rho, \lambda^{(t-1)}, \mu^{(k)}$.*

Proof. Let \mathcal{V} be the subspace of \mathbb{R}^n spanned by the characteristic vectors of X and \overline{X} , and let $\mathcal{W} = \mathcal{V}^\perp$. Note that for any eigenvalue ν , $\begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} \in \mathcal{W} \cap \mathcal{E}(\nu)$ if and only if $\begin{pmatrix} \mathbf{x} \\ -\mathbf{y} \end{pmatrix} \in \mathcal{W} \cap \mathcal{E}^*(\nu)$. The graph G has linearly independent eigenvectors $\mathbf{x}_1, \mathbf{x}_2 \in \mathcal{V}$ with corresponding eigenvalues those of D , while G_X has linearly independent eigenvectors $\mathbf{x}_1^*, \mathbf{x}_2^* \in \mathcal{V}$ with corresponding eigenvalues those of D^* . Moreover, if ρ is the largest eigenvalue of G then we may take $A\mathbf{x}_1 = \rho\mathbf{x}_1$, $A^*\mathbf{x}_1^* = r\mathbf{x}_1^*$, $\mathbf{x}_1^* = \mathbf{j}$ (cf. [4, Theorem 3.9.9]). Since $\mathcal{E}(\mu)$ and \mathcal{W} are subspaces of \mathbf{x}_1^\perp , we have $\dim(\mathcal{E}(\mu) \cap \mathcal{W}) \geq k - 1$. On the other hand, $\dim \mathcal{E}^*(\mu) \leq k - 1$ by Lemma 2.3, and so we deduce that $\mathcal{E}^*(\mu) \subseteq \mathcal{W}$, $\dim(\mathcal{E}(\mu) \cap \mathcal{W}) = k - 1$, and $A\mathbf{x}_2 = \mu\mathbf{x}_2$. Let $A^*\mathbf{x}_2^* = \lambda\mathbf{x}_2^*$. Then $\mu \neq \lambda = p + q - r \in \mathbb{Z}$ and G_X has spectrum $r, \lambda^{(t)}, \mu^{(k-1)}$ (cf. [4, Section 3.6]). Note that $\lambda \neq r$ for otherwise $G_X = (t + 1)K_{r+1}$ and $\mu = -1$, contrary to assumption. We deduce that G has spectrum $\rho, \lambda^{(t-1)}, \mu^{(k)}$. Finally, $\rho \in \mathbb{Z}$ because $\rho = p + q - \mu$. \square

When $G = G_{36}$ and $G_X = L(K_9)$, we have $\mu = -2$, $t = 8$, $k = 28$, $r = 14$, $\rho = 21$, $\lambda = 5$, $p = 12$, $q = 7$, $a = 6$, $b = 21$.

Lemma 3.2. *The matrix $\mu^2 I + A$ is invertible.*

Proof. Since $\mu^2 \notin \{-\rho, -\mu\}$, it suffices to show that $\mu^2 \neq -\lambda$. Now the multiplicities of λ and μ in the strongly regular graph G_X are given by

$$m(\lambda) = \frac{r(r - \mu)(\mu + 1)}{(r + \lambda\mu)(\mu - \lambda)}, \quad m(\mu) = \frac{r(r - \lambda)(\lambda + 1)}{(r + \lambda\mu)(\lambda - \mu)},$$

formulae which follow from [4, Theorems 3.6.4 and 3.6.5]. Suppose by way of contradiction that $\lambda = -\mu^2$. Then $\mu > 0$. Since $m(\lambda) = t$ and $m(\mu) = k - 1 = \frac{1}{2}(t + 1)(t - 2)$, we have:

$$\frac{(t + 1)(t - 2)}{2t} = \frac{m(\mu)}{m(-\mu^2)} = \frac{(r + \mu^2)(\mu - 1)}{r - \mu}. \quad (3)$$

Let $\theta = (r - \mu)/t$. Then

$$0 = \text{tr}(A^*) = \mu + \theta t + t(-\mu^2) + \frac{1}{2}(t + 1)(t - 2)\mu,$$

whence $\theta = \mu^2 - \frac{1}{2}(t - 1)\mu$. Substituting $\mu + \mu^2 t - \frac{1}{2}\mu t(t - 1)$ for r in Equation (3), and dividing by $\mu t(t + 1)$, we obtain:

$$(t - 2\mu)(t - 2\mu - 1) = 2(1 - \mu). \quad (4)$$

Since $\mu \in \mathbb{N}$, the left hand side of (4) is non-negative, while the right hand side is non-positive. We conclude that $\mu = 1$ and $t \in \{2, 3\}$, a contradiction. \square

We are now in a position to prove the following.

Lemma 3.3. *If $4 \leq a \leq t - 2$, the H -neighbourhoods $\Delta_H(u)$ ($u \in X$) form a tight 4-design.*

Proof. By Lemma 2.3, the functions $\langle\langle \mathbf{s}_u, \mathbf{x} \rangle\rangle^2$ ($u \in X$) form a basis for \mathcal{Q}_t . Let

$$\langle\langle \mathbf{x}, \mathbf{x} \rangle\rangle = \sum_{u=1}^n \gamma_u \langle\langle \mathbf{s}_u, \mathbf{x} \rangle\rangle^2, \quad (5)$$

and write $\mathbf{c} = (\gamma_1, \gamma_2, \dots, \gamma_n)^\top$. From Equation (2) we have

$$\mu = \langle\langle \mathbf{s}_i, \mathbf{s}_i \rangle\rangle = \mu^2 \gamma_i + \sum_{u \sim i} \gamma_u \quad (i = 1, 2, \dots, n),$$

whence $(\mu^2 I + A)\mathbf{c} = \mu \mathbf{j}$. In view of Lemma 3.2, we have $\mathbf{c} = (\mu^2 I + A)^{-1} \mu \mathbf{j}$. In the notation of Lemma 3.1, we have $\mathbf{j} \in \mathcal{V}$, while \mathcal{V} is A -invariant since the eigenvectors $\mathbf{x}_1^*, \mathbf{x}_2^*$ form a basis for \mathcal{V} . It follows that there exist $\xi, \eta \in \mathbb{R}$ such that $\mathbf{c} = \begin{pmatrix} \xi \mathbf{j} \\ \eta \mathbf{j} \end{pmatrix}$.

We extend notation in a natural way, so that for example $\Delta_H^*(u)$ denotes the set of vertices in \overline{X} adjacent to u in G_X . For $i, j \in X$, let $r_{ij} = |\Delta_X(i) \cap \Delta_X(j)|$, $s_{ij} = |\Delta_H(i) \cap \Delta_H(j)|$ and $t_{ij} = |\Delta_H^*(i) \cap \Delta_H^*(j)|$. Note that $r_{ij} = |\Delta_X^*(i) \cap \Delta_X^*(j)|$ and $t_{ij} = t - 2a + s_{ij}$. Since $r_{ij} + t_{ij}$ is the number of common neighbours of i and j in G_X , we have

$$r_{ij} + s_{ij} = \begin{cases} 2a - t + e & \text{if } i \sim j \\ 2a - t + f & \text{if } i \not\sim j \end{cases}. \quad (6)$$

Since $\langle\langle \mathbf{x}, \mathbf{y} \rangle\rangle = \frac{1}{4}(\langle\langle \mathbf{x} + \mathbf{y}, \mathbf{x} + \mathbf{y} \rangle\rangle - \langle\langle \mathbf{x} - \mathbf{y}, \mathbf{x} - \mathbf{y} \rangle\rangle)$, Equation (5) yields

$$\langle\langle \mathbf{x}, \mathbf{y} \rangle\rangle = \sum_{u=1}^n \gamma_u \langle\langle \mathbf{s}_u, \mathbf{x} \rangle\rangle \langle\langle \mathbf{s}_u, \mathbf{y} \rangle\rangle.$$

Setting $\mathbf{x} = \mathbf{s}_i$, $\mathbf{y} = \mathbf{s}_j$ we obtain:

$$-1 = \xi(r_{ij} - 2\mu) + \eta s_{ij} \quad \text{if } i \sim j, \quad 0 = \xi r_{ij} + \eta s_{ij} \quad \text{if } i \not\sim j. \quad (7)$$

Thus from (6) and (7) we obtain two sets of simultaneous equations in r_{ij} and s_{ij} :

$$\left. \begin{aligned} r_{ij} + s_{ij} &= 2a - t + e \\ \xi r_{ij} + \eta s_{ij} &= 2\mu\xi - 1 \end{aligned} \right\} \text{ if } i \sim j, \quad \left. \begin{aligned} r_{ij} + s_{ij} &= 2a - t + f \\ \xi r_{ij} + \eta s_{ij} &= 0 \end{aligned} \right\} \text{ if } i \not\sim j.$$

Now $\xi \neq \eta$ for otherwise \mathbf{j} is an eigenvector of A , and G is regular, contradicting Corollary 2.5. Therefore each set of simultaneous equations has a unique solution; in particular, there exist integers e', f' such that

$$|\Delta_H(i) \cap \Delta_H(j)| = \begin{cases} e' & \text{if } i \sim j, \\ f' & \text{if } i \not\sim j. \end{cases}$$

We have $e' \neq f'$, for otherwise $|X| \leq t$ [2, Theorem 1.51]. Thus if $4 \leq a \leq t - 2$ then by Theorem 2.7 the H -neighbourhoods $\Delta_H(u)$ ($u \in X$) form a tight 4-design. \square

In view of Theorem 2.7, it remains to consider four cases: (a) $t = 23$ and $a \in \{7, 16\}$, (b) $a = 3$, (c) $a = 2$, (d) $a = t - 2$.

Case (a). In this case we have $n = 276$, $|X| = 253$, $|\bar{X}| = 23$ and either $a = 7$ or $a = 16$. If $a = 7$ then $D^* = \begin{pmatrix} r-16 & 16 \\ 176 & r-176 \end{pmatrix}$,

whence $176 \leq r \leq 198$. If $a = 16$ then $D^* = \begin{pmatrix} r-7 & 7 \\ 77 & r-77 \end{pmatrix}$, whence $77 \leq r \leq 99$. For these values of r , there is no strongly regular graph of order 276 and degree r ; see for example Brouwer's list of feasible parameters at <http://www.win.tue.nl/~aeb/graphs/srg/srgtab.html>.

Case (b): $a = 3$. Let $\mathcal{D} = \{\Delta_H(u) : u \in X\}$. If $t \geq 7$ then $\bar{\mathcal{D}}$ is a tight 4-design and Theorem 2.7 is contradicted. If $t < 7$ then $t \in \{5, 6\}$ and the multiplicity of μ in G_X is 9, 14 respectively. If $t = 5$ then either $G_X = L(K_6)$ with $\mu = -2$ or $G_X = \overline{L(K_6)}$ with $\mu = 1$. In the former case, $D^* = \begin{pmatrix} 6 & 2 \\ 4 & 4 \end{pmatrix}$, and so $H = K_5$; but the graph obtained from K_5 by adding a vertex of degree 3 does not have -2 as an eigenvalue (see Lemma 2.2). In the latter case, $D^* = \begin{pmatrix} 4 & 2 \\ 4 & 2 \end{pmatrix}$, and so H is a 5-cycle; but then not all 3-subsets of \bar{X} can be H -neighbourhoods in G [4, Example 5.2.3]. Now suppose that $t = 6$. Then $k = 15$ and we have $b = ka/t = 45/6$, a contradiction.

Case (c): $a = 2$. Here the H -neighbourhoods in G are all the 2-subsets of \bar{X} , and their intersection numbers are necessarily 0 and 1. We have

$$D^* = \begin{pmatrix} r-t+2 & t-2 \\ \frac{1}{2}(t-1)(t-2) & r - \frac{1}{2}(t-1)(t-2) \end{pmatrix},$$

whence $\lambda = r - \frac{1}{2}(t-2)(t+1)$. Now

$$0 = \text{tr}(A^*) = r + t(r - \frac{1}{2}(t-2)(t+1)) + \frac{1}{2}(t+1)(t-2)\mu,$$

whence

$$\mu = t - \frac{2r}{t-2}. \quad (8)$$

A 2-subset of \overline{X} intersects precisely $2t - 4$ other 2-subsets of \overline{X} . Hence if $(e', f') = (1, 0)$ then each vertex in X has $2t - 4$ neighbours in X , and so $2t - 4 = r - t + 2$. Thus $r = 3(t - 2)$, and we see from Equation (8) that $\mu = t - 6$. Now $r \geq \frac{1}{2}(t - 1)(t - 2)$ and so $t \leq 7$. Since $\mu \neq -1$ or 0 , we have $t = 4$ or $t = 7$. If $t = 4$ then

$$D^* = \begin{pmatrix} 4 & 2 \\ 3 & 3 \end{pmatrix} = D,$$

whence G is 6-regular, a contradiction. If $t = 7$ then $r = 15$, $\mu = 1$ and \overline{X} is an independent set. Equating diagonal entries in Equation (1), we find that $a = 1$, a contradiction.

If $(e', f') = (0, 1)$ then each vertex in X has $2t - 4$ non-neighbours in X , and so $2t - 4 = \frac{1}{2}t(t - 1) - 1 - (r - t + 2)$. We find that $r = \frac{1}{2}(t - 1)(t - 2)$, $\mu = 1$ and \overline{X} is independent, leading to the same contradiction as above.

Case (d): $a = t - 2$. In this case we have $D^* = \begin{pmatrix} r - 2 & 2 \\ t - 1 & r - t + 1 \end{pmatrix}$, whence $\lambda = r - t - 1$. Now

$$0 = \text{tr}(A^*) = r + t(r - t - 1) + \frac{1}{2}(t + 1)(t - 2)\mu,$$

and so

$$\mu = \frac{2(t - r)}{t - 2}.$$

For distinct $u, v \in X$, let

$$|\Delta_H^*(u) \cap \Delta_H^*(v)| = \begin{cases} e^* & \text{if } u \sim v, \\ f^* & \text{if } u \not\sim v \end{cases},$$

so that $\{e^*, f^*\} = \{0, 1\}$.

If $(e^*, f^*) = (0, 1)$ then each vertex of X has $2t - 4$ non-neighbours in X , and so $r - 2 = \binom{t}{2} - (2t - 4) - 1$, whence $r = \frac{1}{2}(t^2 - 5t + 10)$ and $\mu = 5 - t$. Since $r - t + 1 \leq t - 1$, we have $(t - 2)(t - 7) \leq 0$, whence $t \in \{4, 5, 6, 7\}$. If $t = 4$ then $r = 3$, $\mu = 1$ and G is 3-regular, contradicting Theorem 2.4. If $t = 5$ or 6 then $\mu = 0$ or -1 , contrary to assumption. If $t = 7$ then $a = 5$, $\mu = -2$, $H = K_7$ and we obtain a contradiction from Lemma 2.2.

If $(e^*, f^*) = (1, 0)$ then each vertex of X has $2t - 4$ neighbours in X , and so $r = 2t - 2$, $\mu = -2$. Moreover, $H = K_t$ and Lemma 2.2 yields

$$(t - 2)^2 - (t + 1)(t - 2) + 2(t + 1) = 0.$$

It follows that $t = 8$. Since G is determined by H and all 6-subsets of \overline{X} as H -neighbourhoods of vertices in X , we conclude that $G = G_{36}$.

This completes the proof of Theorem 1.1

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